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MELTING INFLUENCES ON THE COMPUTER
FORECAST OF WIND DRIFT AND
CONCENTRATION OF SEA ICE

KENNETH M. IRVINE

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Kenneth M. Irvine

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OF SEA ICE

by

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Lieutenant, United States Navy

Submitted in partial fulfillment of
the requirements for the degree of
MASTER OF SCIENCE

United States Naval Postgraduate School
Monterey, California

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This work is accepted as fulfilling
the thesis requirements for the degree of
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ABSTRACT

Knodle has developed a computer program to provide five-day forecasts of the wind drift and concentration of sea-ice [1]. One of the problems not considered in the program is the effect of melting. Melting influences concentration in two ways. It reduces the amount of ice directly, and changes in thickness and concentration change the wind drift. A model to describe how ice-melt decreases thickness and concentration is developed and programmed. The results are used to modify the input data in Knodle's wind drift forecast; forecasts are compared with those based on wind drift alone. The modification enhances the use of the program as a forecast tool with the addition of normally available data.

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1. Introduction

A sea-ice forecast that is accurate and timely has assumed increasing importance as operations in the Arctic areas increase. Reconnaissance and commercial flights, basic research, submarine operations, exploration, and resupply operations are all safer, more economical, and efficient if strategic and tactical commanders or project managers have available accurate forecasts.

In several areas of meteorological analysis and forecasting the large, high-speed digital computer has become a valuable aid. The results, notably in some upper-air weather charts, are as good, if not better, than those produced by slower subjective means. Significant steps in the programming of oceanographic forecasts have been taken and show promise. Machine methods of predicting sea-ice represent an improvement over other techniques in that 1) results are immediately available for large areas once inputs are made, 2) retention of computed values and ease of modification enhance the continuity of the forecast, 3) once the program is operating relatively little skill is required to produce the forecast, 4) at least some idea of the sea-ice behavior is available for areas not frequently observed.

There are some disadvantages to computer methods, among them: 1) putting observations into digital form may be difficult and time consuming; 2) grid size limits the treatment of important details; 3) errors introduced by finite approximations may lead to instabilities.

Knodle in 1964 proposed and tested a digital model to give five-day forecasts of the wind drift and concentration of sea-ice [1]. Lacking in Knodle's model is consideration of melting, which he feels is a major source of error. Melting changes both the thickness and the concentration, upon which depends the wind drift.

Another influence on drift, not considered in the Knodle program, nor in the one proposed here, is that of currents. Little is known of the currents in Baffin Bay, the area for which this work was done, as most measurements were taken in ice-free regions, late in the summer season. Results of program forecasts show areas where it appears very likely that errors due to current effects are important.

This paper will present a model of the melting effects and incorporate it into the wind drift program. Then the results of this modified program are compared to the original forecast to see if melting indeed contributes significantly to forecast accuracy.

2. Models for the melting effects

Melting of sea-ice may be separated into three major processes; thickness reduction, concentration reduction, and puddling of the ice surface. Each process may now be considered separately. Zubov has proposed mathematical models for the first two processes, while a modification of the concentration reduction leads to an expression for the puddling effect [2].

The first item to consider is the thickness reduction model. For this Zubov makes the assumptions that there exists a flat, uniform ice field, the amount of incoming radiation remains unchanged for the period of time under consideration, and the ability of the ice to absorb heat increases proportionally with time. Further, he assumes that all the heat absorbed by the ice is used to reduce the thickness. Equation (1) follows from these assumptions.

$$h' = \frac{bT^2}{2\rho_i\lambda} \quad (1)$$

where h' = thickness of ice melted (cm)

bT = coefficient of heat absorption
(cal/cm²-day)

ρ_i = ice density (gm/cm³)

λ = heat of fusion (cal/gm)

T = time for which reduction
is to be computed (day)

In this equation the constant b is to be evaluated by empirical means.

Next consider the process of concentration reduction. In ice areas of less than 10/10 coverage some heat will be absorbed by the water. Zubov proposes that this heat alone is used to reduce the area of the adjacent floes, and that it is entirely used in this process. This seems reasonable considering the albedos of the two surfaces and the low water temperatures near the ice while melting is in progress. The heat is transmitted to the ice by mechanical mixing caused by winds, tides, and currents, and by thermo-haline convection. The resulting equation is expressed by Zubov in terms of the ice-free water concentration.

$$w_t = w_o e^{\frac{mT}{h\rho_i\lambda}} \quad (2)$$

where w_t = area of ice-free water (tenth)

w_o = original ice-free area (tenth)

m = heat absorbed ($\text{cal}/\text{cm}^2 \text{ day}$)

h = ice thickness (cm)

ρ_i = ice density (gm/cm^3)

λ = heat of fusion (cal/gm)

T = time for which reduction is to be computed (day)

The last effect considered is that due to puddling on the ice surface. The necessity for this, or some like expression, is seen by examination of equation (2), which does not apply in situations of 10/10 ice coverage. It was felt that it would be unrealistic to assume that areas of total coverage would remain throughout the season.

Thus, a mechanism was required which would reduce the areas of total coverage as the season progressed. Puddling of the ice surface seemed to provide an answer. If a puddle of specified area is heated, the heat absorbed will increase the area of the puddle and its depth. The depth increase results in a reduction of the thickness of the ice layer below the puddle. Since the puddle absorbs more heat than the surrounding ice, this thickness decrease should proceed at a faster pace than in unpuddled regions, and eventually the puddle should reach the bottom, thus decreasing the concentration at that location. For this thickness decrease I have assumed the following expression.

$$h_p = \frac{m' T}{\rho_i \lambda} \quad (3)$$

where h_p = thickness of ice melted (cm)
at the bottom of the puddle
in time T

m' = amount of heat absorbed and used
to increase puddle depth (cal/cm² day)

ρ_i = ice density (gm/cm³)

λ = heat of fusion (cal/gm)

T = time during which reduction
takes place (day)

The determination of the quantity m' is discussed in Section 3. Equations (1), (2), and (3) form the basis for the forecasting equations developed in the next section.

3. Developement of computational equations

The quantities to be forecast are ice concentration and thickness changes due to melting effects alone. In all but areas of 10/10 coverage, equations (1) and (2) provide these results. The role played by equation (3) will be discussed later. Of the required inputs for these three equations, initial values of concentration, thickness, and puddling are available from the standard ice reports from reconnaissance flights, icebreakers, etc. What remains is to assign values to the density, heat of fusion, b , m , and m' . Each of these parameters will now be discussed and the final form of the equations will be derived.

Common to all models is ice density. Various investigators, principally Untersteiner, have shown that even during the melting season the ice density does not vary by more than $\pm 0.05 \text{ gm/cm}^3$; so the commonly used value of 0.9 gm/cm^3 is used throughout [3]. Also appearing in all equations is the heat of fusion. This quantity has been reported by Sverdrup, Johnson, and Fleming to vary over a wide range with changes in both temperature and salinity [4] (after Malmgren). Figure (1) shows the change with salinity for two temperatures. Since melting largely takes place at about -1°C to -2°C , curves (1) and (3), curve (2) of figure (1) is drawn for a mean temperature of -1.5°C . Malmgren has also stated that sea-ice rarely exceeds a salinity of 7%. From this discussion it can be seen that the heat of fusion can be approximated by equation (4).

Figure 1
Heat of Fusion vs Salinity

$$\lambda = -3.3 S + 80.5 \quad (4)$$

where λ = heat of fusion (cal/gm)

S = salinity (parts per thousand)

To complete the prediction of the heat of fusion at any time during the melting season it is necessary to know how the salinity of sea-ice changes as the season progresses. This quantity is rarely reported or measured in Baffin Bay. Experiments and observations to date are not conclusive on this point. As a first approximation it was decided to assume that the maximum salinity of 7% (after Malmgren) was the salinity of the upper layer of the ice throughout the region at the start of the melting season. This assumption is more nearly correct when applied in equation (1) where the melting is a surface phenomenon, than in equation (2) where melting occurs on the sides of floes, where the initial salinity may be lower. For the duration of the season a linear decrease of salinity with time was assumed. Equation (5) results.

$$S = -0.063 T' + 7\% \quad (5)$$

where S = salinity (parts per thousand)

T' = elapsed time since the start of
the melting season (day)

To arrive at this expression the initial value of salinity was taken to be 7%. Eight years of data from NAVOCEANO reports were used to determine a mean melting season for the region of 111 days with a $\sigma = \pm 10$ days [5]. Substituting (5) into (4) yields equation (6), the final form of the

equation for predicting the heat of fusion at any time during the melting season.

$$\lambda = 0.208 T' + 57.4 \quad (6)$$

The coefficient bT in equation (1) arises from the initial assumption that the quantity of heat absorbed by the ice is proportional to time. The actual relationship is very complex, depending upon changes in the physical structure of the ice, its albedo, puddling, wind speed, temperature, humidity, and other factors. For this model, however, b is assumed constant and can be evaluated. In Baffin Bay the entire ice field is presumably zero at the end of the melting season; if one can specify the initial ice thickness and the length of the melting season, equation (1) can be applied. Using the eight years' data this evaluation was accomplished [5]. It was found that $b = 1.5 \text{ cal/cm}^2 \text{ day}$ with $\sigma = \pm 0.1$. Zubov found $b = 1.6$ in the Kara Sea. The value found above was used in the initial forecasting attempts. To maintain program flexibility it is entered as a variable and may easily be changed should forecast results indicate the necessity.

The next parameter considered is the m occurring in equation (2). This is the heat flux entering the water. There are a number of ways to arrive at a representative value of m . Zubov considered $300 \text{ cal/cm}^2 \text{ day}$ to be correct at 75N latitude. This is a climatological figure with

allowance for cloudiness and optical transparency of the water. This value was used initially. Laevastu has summarized several attempts to predict this figure and has a series of nomograms for forecast purposes; these were adopted in this study [6]. These nomograms have been programmed for digital computation but the programmed version was not used in this effort. Tabata also has a simple forecast scheme for use in non-advective areas which might be used [7].

The final forms for computation are now found. Substitution of (6) into (1) gives

$$h' = \frac{b T^2}{2 \rho_i' (.208 T' + 57.4)} \quad (7)$$

Again using (6), equation (2) becomes

$$W_t = W_0 e^{\frac{m T}{h \rho_i' (.208 T' + 57.4)}} \quad (8)$$

To summarize, other values which were used in the program were:

$$\rho_i' = 0.9 \text{ gm/cm}^3$$

$$b = 1.5 \text{ cal/cm}^2 \text{ day}$$

$$m = \text{forecast from weather parameters using} \\ \text{Laevastu nomograms (cal/cm}^2 \text{ day)}$$

In equation (3) describing puddle growth, the same values of ρ_i' and λ were used as in the preceeding discussion. The essential problems here are to determine when this expression applies and what value should be assigned

the parameter m' . The equation is used to determine when puddling has reduced concentration to less than $10/10$. It therefore applies only for areas of $10/10$ concentration in which puddling is reported. When puddle depth equals ice thickness, concentration is automatically reduced. Equation (3) states that all puddles in an area will melt through at the same time. Thus, in areas of $10/10$ concentration, the concentration should be reduced an amount equal to the puddled area. The original thickness of the ice is not uniform, however, and as a result this much reduction in concentration probably will not occur. For this reason the concentration is reduced to $9/10$. As the season progresses this figure should be adjusted to show greater reductions. The thickness of the floes is given by equation (7).

The evaluation of the quantity m' was done as follows. Examining several seasons' ice reports showed that within the first 40 days the puddle area growth was rapid, reaching generally $6/10$ during this time. After 40 days the area growth slowed considerably and rarely exceeded $8/10$ for the rest of the season. Therefore it was assumed that at the start of the season the amount of heat absorbed and used to increase puddle depth was 0.1 of that absorbed in the puddle, the remaining 0.9 being used for areal growth. Further, the heat used to increase puddle depth increased linearly with time until at 40 days 0.8 of the heat was used for this depth increase and the amount remained

constant for the balance of the season. It was further assumed that if the reported puddle area was 6/10 prior to the 40 day time the figure 0.8m would be used. These assumptions, expressed as equations (9), were then incorporated into the program.

$$m' = \begin{cases} 0.1m + 0.0175T' & \left\{ \begin{array}{l} T' \leq 40 \text{ days} \\ \text{Puddling} < 6/10 \end{array} \right. \\ 0.8m & \left\{ \begin{array}{l} T' > 40 \text{ days} \\ \text{Puddling} \geq 6/10 \end{array} \right. \end{cases} \quad (9)$$

The quantities have the same definitions as before. Substitution of equation (6) into (3) gives

$$h_p = \frac{m'T}{\rho_i (1.208T' + 57.4)} \quad (10)$$

with m' being determined by equation (9).

4. Programming technique

The approach to producing the final forecast was to first devise a program which would forecast concentration and thickness in 24-hour steps from consideration of melting effects. This is Program ICEMELT, **Appendix A**. It is the result of applying equations (7), (8), (9), and (10). The program is written in the FORTRAN 60 language for the 1604 computer. After this program was adjusted to produce fields that looked like nature to a degree, it was incorporated into Program ICEGRID to produce Program ICEGRID MODIFIED, **Appendix B**. The adjustments mentioned above established various continuity and error checks at program exits. The need for such adjustments became apparent when viewing initial outputs of the program. Following the establishment of ICEGRID MODIFIED, forecasts with real data were made using this program. Results are reported in a later section.

All programs use a 546 grid-point array of dimensions 26 by 21 to hold the data. All print outputs leave out the outer edge of this array. The distance between grid points is determined by the scale factor. A scale factor of one gives 60 nautical miles between grid points, two for 30 nautical miles, and so on. All forecasts made for this study used a scale factor of two. Scale factors larger than one, i.e., grid sizes larger than 60 nautical miles, do not provide the detail it was felt desirable to have.

Large grids also give rise to location errors. With a scale factor of two this error may be as large as 15 nautical miles. Another factor to consider at a larger grid size is the fact that the plane grid herein used will no longer be a good approximation of the spherical earth. There exist methods for handling this problem, but with the grid size used they were not required.

Data for the forecasts were obtained principally from the NAVOCEANO reports for the region [5]. Of course, in an operational situation the current weather prognoses and reconnaissance flight data would be used.

The forecast length is five days at 24-hour intervals. This conforms to standard practice in the operational forecast schedule. Smaller step sizes are not practicable with the current program because of the difficulty of forecasting the short-term fluctuations of the weather parameters. The inherent errors and instabilities of the program are cumulative in nature. The five-day length of the forecast proved practical in effective isolation of these errors.

In program ICEGRID MODIFIED the outputs are concentration fields, direction fields, and distance of movement fields, forecast for five successive days following the input day. In addition the user may obtain the results of the incorporated ICEMELT by proper entry on the first data card. Land points are entered as the value 2.0 in the concentration field. Appropriate program instructions check these land points, and continuity between concentration

and thickness, for proper entry into the computation equations. The program as it is presently written uses forecast values as input data for the next days' forecast.

In addition to these programs a very simple error analysis program was written to calculate the RMS-error of the concentration field, using equation (11).

$$RMS - error = \sqrt{\frac{\sum f_i x_i^2}{N}} \quad (11)$$

where $f_i =$ one

$x_i =$ difference between the observed
and forecast concentrations at a
grid point

$N =$ total number of the sample

Input data are the concentration fields, observed and forecast, for a specified day. The output is a print of the RMS-error.

5. Results

First, computer runs were made using Program ICEMELT on observational data. Five-day forecasts which approximated nature were obtained. An m-value of $300 \text{ cal/cm}^2 \text{ day}$ was used in these runs. No attempt, other than a subjective judgement and an arithmetic check, was made to verify these forecasts, since the wind drift would be the dominant feature. It was noted that the thicknesses were of the right order of magnitude, but that concentration changes appeared larger than one would normally expect from melting influences. It was resolved that a more accurate attempt would be made to forecast the m-value for ensuing forecast periods. The climatological figure used by Zubov for an entire season appears unsatisfactory for the short-term forecast.

Following these first attempts, Program ICEGRID MODIFIED was used to forecast for the period 11-16 June, 1953. An m-value of $225 \text{ cal/cm}^2 \text{ day}$, derived from the Laevastu nomograms, was used. In this combined program of wind drift and melting effects the concentration results again showed excessive concentration reductions.

Upon re-examination of the assesment of m it was discovered that a much wider variability of this figure than anticipated is quite possible. Within the forecast area it may range from $20 \text{ cal/cm}^2 \text{ day}$ to above $200 \text{ cal/cm}^2 \text{ day}$. To use just one value of m appears arbitrary in view of this, but it was found that the use of a conservative figure gave reasonable results.

With this in mind, examine figure (2), the forecast for 15 June, 1953, which was made using a conservative m -value of $35 \text{ cal/cm}^2 \text{ day}$. The lines in the figure delineate the edge of the ice field from the observed data, ICEGRID, and ICEGRID MODIFIED. An improvement over the Knodle forecast may be seen in some areas. The tendency of ICEGRID MODIFIED to over-forecast areas of initial high and low concentrations is especially evident in the area due North of Baffin Island. Observational data for the area along the north edge of the island show very low concentrations but not the open water forecast. It is true, however, that areas of increasing or decreasing concentration appear to be correctly located, although the magnitudes are in error. This is day four of the forecast. On day five results were unusable due to excessive drift and melt.

The next forecasting trial was for the period 12 to 17 May, 1959. The 17 May forecast is reported as figure (3). An important feature of this example is that the line delineating the edge of the ice has been subjectively smoothed. The basic guidelines for this smoothing were the original input data, previous days' forecasts, and the knowledge that ICEGRID MODIFIED tends to over-forecast areas of low and high concentrations. The decision to employ subjective smoothing was greatly aided by the results of the RMS error analysis, reported in Section 6. As can be seen from figure (3) this smoothing improved the forecast materially.

Since it seemed likely that the smoothing might be influenced by having available the Knodle forecast and the observed edge of the ice, a run of ICEGRID MODIFIED was made for the period 4 through 8 June, 1957. The 8 June forecast is shown as figure (4). The smoothed line locating the edge of the ice field was drawn following the precepts mentioned without prior knowledge of the observed edge. Again results are in accord with the observed edge.

These three periods were the only ones in which forecasts were made due to time limitations. They represent a total of 15 forecast days from three different years and appear to yield useful information. Some of the difficulties encountered would not be present in field forecasting. The forecaster would have an up-to-date synoptic picture coupled with a more extensive background. There would not be the delays in receiving results that were present here due to the extensive student use of the computer.

Further sections discuss errors, recommendations, and conclusions on the basis of these results.

Forecast Concentration
8 June, 1957
Figure 4

6. Limitations and error analysis

Objective error analysis

The program described in Section 4, which produced a RMS-error of concentration, was applied to the results of ICEGRID MODIFIED, using observed data for the comparison. For 15 June, 1953 the error was 0.24. This error was in excess of the observational error, estimated to be 0.1. If it can be shown that a large portion of this error was contributed by the areas of high and/or low concentration more accurate subjective judgements of the forecast could be made. Therefore, a run was made omitting those areas with a forecast value of 0/10 concentration, giving a RMS-error of 0.14. The next step was to eliminate, in addition, grid locations which had a forecast value of 10/10. The RMS-error now became 0.06, which is less than the observational error. Thus, by eliminating from the forecast both zero and total coverage areas an accurate forecast was obtained.

For the same date the RMS error of the Knodle program, ICEGRID, was 0.1. Thus, it can be seen that program ICEGRID MODIFIED has the possibility of being superior to ICEGRID if a method of dealing with the areas which forecast excessively is devised. The program is more accurate except in these areas.

It appears that computer instability is at fault, even with only five-day steps. A more sophisticated method of

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step-wise approximation, such as the Runge-Kutta model, time averages using past days' results, space averaging about surrounding grid points in the melt forecast portion of the program, or some similar treatment might smooth out or decrease this instability. However, none of these methods were applied in this thesis.

The thickness forecast of ICEMELT was spot-checked by hand calculation. Starting with the input thickness the hand calculation was performed for the five days and compared with the observed thickness at the grid location at the end of the forecast period. In all cases, the forecast value was within the observational error. This portion of the forecast depends on b . If the melting season is radically different from the climatological mean, or the original ice thickness is anomalous, a climatological b will no longer be proper. However, the program permits the forecaster to change b if this appears to be necessary.

Heat budget

In the heat budget expressions two coefficients must be determined empirically, b , which is related to heat absorption by the ice, and m , the heat absorbed by the water. Recall that b was calculated on the basis of total disappearance of the ice at the end of the season. Since much of the melt takes place in puddled areas, other melting stems from heat in the surrounding waters, and considerable

ice is removed advectively, this b is probably too large. Melting seasons may vary considerably. For example, Melville Bight, during 1965, had anomalous temperatures and 10/10 ice, a highly unusual situation. It is unrealistic to assume that the b -value of previous years would apply in this situation.

Perhaps b can be evaluated at data points where advection is small; then adjustments can be made during the season from icebreaker reports and reconnaissance flights. By hand this would be tedious, but using a computer it becomes feasible. For five-day intervals ICEGRID MODIFIED is not sensitive to thickness changes, which depend upon b . However, one of the aims of the program is to provide information about little observed areas, so the influence of b on h' must be considered over longer periods. In this time frame, thickness changes do have a significant effect and the b -value assumes new importance.

As was discussed in Section 5, a very conservative figure for m had to be used to produce usable forecasts. This value was an order of magnitude smaller than the climatological figure for the area. Too few cases were tried to establish whether this should be true in general, but it does cast a shadow on the ability of the equations and assumptions to provide a short-term forecast. To determine more exactly the validity of these items an m -value for each grid location could be forecast. Other heat distributing processes, particularly advection, could be considered

to modify the m -values used here. Further, the m -value determines what is to be used for m' in the puddling expressions, so error in m can be re-introduced into the program. The determination of m' is considered to be a first approximation only. More investigation of the heat budget in puddles is necessary.

Permanent currents

The program does not consider the effects of currents. Observed advection of ice by currents often has the same magnitude as the wind drift component; so this forms a major possible source of error. Currents could be incorporated into the prediction and would probably improve results.

Hummocking and ridging

The roughness coefficients are assumed to be constant during the drift period and over the entire space field. Changes in hummocking and ridging would affect calculations of wind drift by changing the roughness parameters; they also change the melting process. For melting, a flat, uniform field is assumed, however, the slopes of the hummocks and ridges absorb heat differently than a flat surface, thus changing melting rates, the formation of puddles, and the observed thickness. However, the size of these roughness features is not reported, only their presence; so it is only by some qualitative means that they could be presently accounted for. In addition to their indirect influences, hummocking and ridging

affect both surface and subsurface navigation, and travel over the ice; more detailed and quantitative reports on their characteristics are, therefore, doubly desirable.

Transport from outside the area

No consideration is given either to ice transport or to horizontal heat advection across the boundaries. These omissions may lead to erroneous forecasts near the boundaries. There are several means of dealing with this. A partial solution used in the existing program is to omit one row and one column of data at the edge in the final printed result. Another method for treating boundary effects is to change the data at the boundaries as common sense and climatology suggest, ignoring forecast values there.

Near shore ice drift

Near shore ice drift has a quite different character than drift offshore. To adequately described it would require entry into the machine with not only boundary location but orientation at each point. At present ICEGRID MODIFIED considers ice concentrations at adjacent land points as 0/10 and 10/10 for offshore and onshore winds, respectively, for computing concentration changes near shore (after Knodle).

Transient states in the ice field

Transient states may be introduced in the ice forecast by short-term fluctuations of the wind field or insolation. If these fluctuations are of a duration less

than a day the program will not detect them. In addition transients may be induced from the change from one steady state regime to another, due to inertia, even though diurnal variations are not considered. The program has no means of dealing with these, only the steady state condition is recognized.

Observational data

At the present time the principal source of data is U.S. Navy reconnaissance flights from Argentia, Newfoundland, supplemented by icebreaker reports. The flights are generally twice weekly, and cover only that portion of the area most critical for resupply operations to Greenland bases. Thus, the location of the edge of the pack is well defined, leads close to Greenland are known, but little is observed of the rest of the area. Observation is largely subjective and may contain considerable error. As presently reported, data are not readily adaptable to digital methods. The reports must be plotted on charts before being transferred to punch cards. This is time consuming and some other means must be found before a digital forecast can compete with hand forecasts on a time basis.

Further, weather data for the region are sparse. This means that an accurate heat budget forecast and wind field prognosis are extremely difficult.

Programming language

The language used was FORTRAN 60, which is easy for the tyro programmer to understand but has several disadvantages. Wind forecasts are not available in this language; so the wind forecast must be derived from prognostic charts, then entered on punch cards. Again a loss of time results. In all, it takes 15 hours to ready a data deck for the forecast. In an operational situation this time could be halved but it is still long compared to the five minutes it takes the computer to make the forecast.

7. Recommendations

Several considerations are invited by a review of the preceeding sections. There is a need for more data and for better means of observation . Remotely controlled nuclear powered stations may in the future provide some answer. Satellite observations could prove helpful, although at present the small scale features of interest are not detected by the TIROS system.

The program should be written in language compatible with existing weather programs, so that direct input from reporting stations to computer is possible.

The existing program should be modified to include at least permanent currents. A smoothing function should be employed to control stability. With these modifications a large number of forecasts should be made and verified, and a statistical error analysis should be performed. An attempt should be made to obtain better m and b-values, perhaps including laboratory studies of melting of ice. Changes of the heat of fusion with time should be more fully investigated.

Another approach to the melting effects could be made using the degree-warming-day concept and results compared with ICEMELT.

8. Conclusions

In the foregoing sections the developement of a modified wind drift program to include melting effects has been shown.

It is concluded that melting effects are pertinent to improvement of forecast accuracy. However, it is also noted that further work is required to produce smoother and more stable forecasts using this program. Although data preparation detracts from the speed of this objective method, it is felt that it is superior to hand forecasts by subjective means because of its potential accuracy and detail, and because identical results will be obtained no matter who does the work, provided the input data are the same.

Further, there does exist a great need for improved data gathering networks in the Arctic region. For all the recognition paid this area by the world, adequate physical description is lacking.

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APPENDIX A

PROGRAM ICEMELT

Description

This program computes sea-ice concentration and thickness using equations after Zubov. Thickness and concentration fields are for a grid of 546 points dimensioned 21 by 26. Inputs are ice concentration, thickness, puddling, coefficient of heat absorption, density, elapsed time of melting season, and scale. The purpose of the program is to produce five-day forecasts of thickness and concentration due to melting effects alone.

Table A-1 defines the variables in the program language. The complete program is listed following this discussion.

Data Input

Data input is accomplished by IBM cards with the values punched on them in decimal form. Constants are also entered in this fashion.

The first data card specifies the scale, the base latitude, ice density, the constant b , the m -value, and the elapsed time since the melting season began. Neither scale nor base latitude are used in the program although they could be printed out as a handy index. The base latitude establishes the northern-most boundary of the grid and is always the latitude of the boundary plus the inverse of the scale factor (after Knodle). The next 14 cards specify the concentration field. Land points are entered as 2.0

Following these are 14 cards for the thickness. Land points may be entered as 0.0 or 9.0. The last 14 cards are the puddling field entered in tenths.

Output of results

Five forecasts of concentration and five of thickness are printed; one of each on each day. On all printed grids the outer boundary points used in computation are omitted. Preceding all the forecast results is a print of the input concentration.

TABLE A-1

Definitions of variables in ICEMELT*

CONCICE	ice concentration
THICK	ice thickness
XELT	thickness melted
COMP	input thickness converted to centimeters
TIME	length of forecast
WATEO	concentration of ice-free water
DEWATE	change in ice-free water surface
PUDLE	puddling data field
EXTRA	exponent
DTHICK	thickness decrease underneath puddle
RHEAT	amount of heat used to increase puddle depth, m'
SCALE	grid scale factor
BLAT	base latitude
RHO	ice density
BEE	constant b
HEAT	amount of heat absorbed in the water
YTIM	elapsed time since the start of the melting season

* Note: Some variables in the DIMENSION statement of ICE-MELT are not used in the program and are therefore not defined. See Appendix B


```

PROGRAM ICEMELT
C THIS PROGRAM COMPUTES THICKNESS AND CONCENTRATION FROM
C MELTING EFFECTS ALONE

    DIMENSION CONCICE(26,21),VELWIND(26,21),DIRWIND(26,21),THICK
    1(26,21),TEMPICE(26,21),UELX(26,21),VELY(26,21),DIST24(26,21),
    2DIRICE(26,21),XELT(26,21),COMP(26,21),ZICE(26,21),WATEO(26,21),
    3DEWATE(26,21),PUDLE(26,21),EXTRA(26,21),DTHICK(26,21)
    READ 55,SCALE,BLAT,RHO,BEE,HEAT,YTIM,OPT
    C SCALE FACTOR FOR THE GRID.
    55 FORMAT(7F10.5)
    C BASE LATITUDE.
    1001 FORMAT(2F10.5)
    READ 10,((CONCICE(I,J),J=1,21),I=1,26)
    C READ IN INITIAL CONCENTRATION.
    10 FORMAT(39F2.1)
    READ 237,((THICK(I,J),J=1,21),I=1,26)
    237 FORMAT(39F2.0)
    READ 23,((PUDLE(I,J),J=1,21),I=1,26)
    23 FORMAT(39F2.1)
    PRINT 777,((CONCICE(M,N),N=2,20),M=2,25)
    777 FORMAT(F9.2,18F6.2////)
    TIME=1
    DO 1964 KJ=1,5
    DO 11 JI=1,26
    DO 11 KI=1,21
    IF(THICK(JI,KI)-9.0)13,14,14
    C CONVERTS FEET TO CENTIMETERS
    13 COMP(JI,KI)=THICK(JI,KI)*12.0*2.54
    C COMPUTES AMOUNT MELTED
    XELT(JI,KI)=(BEE*TIME**2.0)/(2.0*RHO*(.208*YTIM+57.4))
    THICK(JI,KI)=COMP(JI,KI)-XELT(JI,KI)
    IF(THICK(JI,KI))208,208,107
    208 THICK(JI,KI)=0.0
    GO TO 107
    14 THICK(JI,KI)=9.0
    107 IF(CONCICE(JI,KI)-2.0)108,109,109

```



```

109 CONCICE(JI,KI)=2.0
GO TO 11
108 WATEO(JI,KI)=1.0-CONCICE(JI,KI)
IF(WATEO(JI,KI)-1.0)17,28,28
28 CONCICE(JI,KI)=0.0
THICK(JI,KI)=0.0
GO TO 11
17 IF(CONCICE(JI,KI)-1.0)27,18,18
18 IF(PUDLE(JI,KI))11,11,467
COMPUTES CONCENTRATION CHANGE
27 EXTRA(JI,KI)=HEAT*TIME/(RHO*THICK(JI,KI)*(.208*YTIM+57.4))
DEWATE(JI,KI)=WATEO(JI,KI)*EXPF(EXTRA(JI,KI))
CONCICE(JI,KI)=1.0-DEWATE(JI,KI)
THICK(JI,KI)=THICK(JI,KI)*.39/12.0
IF(THICK(JI,KI))113,113,11
GO TO 11
467 IF(PUDLE(JI,KI)-.6)432,609,609
432 IF(YTIM-40.0)546,546,609
546 RHEAT=.1*HEAT+(.0175*YTIM)
GO TO 611
609 RHEAT=.8*HEAT
611 DTHICK=(RHEAT*TIME)/(RHO*(.208*YTIM+57.4))
IF(DTHICK(JI,KI)-THICK(JI,KI))19,20,20
C CONVERTS CENTIMETERS TO FEET
19 THICK(JI,KI)=THICK(JI,KI)*.39/12.0
IF(THICK(JI,KI))155,155,36
155 THICK(JI,KI)=0.0
GO TO 36
20 CONCICE(JI,KI)=.9
THICK(JI,KI)=THICK(JI,KI)*.39/12.0
IF(THICK(JI,KI))113,113,11
113 THICK(JI,KI)=0.0
GO TO 11
36 CONCICE(JI,KI)=1.0
11 CONTINUE
IF(OPT)762,791,791

```



```
762 PRINT 47((CONCICE(M,N),N=2,20),M=2,25)
  47 FORMAT (F9.2,18F6.2////)
PRINT 901,((THICK(M,N),N=2,20),M=2,25)
901 FORMAT(F9.2,18F6.2////)
791 YTIM=YTIM+1.0
      END
      END
```


APPENDIX B
PROGRAM ICEGRID MODIFIED

Description

This program computes wind drift of sea-ice with a modification for melting. Computations are for a 546 point array utilizing latitude, ice thickness, concentration, wind speed, and wind direction as inputs. The purpose is to produce five-day forecasts of concentration, direction and distance of movement. The user has the option of receiving a print of the melt effect concentration and thickness forecasts by proper entry on the first data card.

Table B-1 defines the variables used in the program. The complete program is listed following this discussion.

Data input

Data input is accomplished by using values punched on IBM cards. The first data card contains the scale factor, the base latitude, which is always the northern-most boundary of the grid, plus the inverse of the scale factor. This card next has the ice density, the constant b , the value of m , and the elapsed time since the start of the melting season. The last field on the card is used to indicate if a print of the melt forecast is desired. If the field is left blank, the print will not occur; if it is entered with any negative number, the melt forecast results will be printed. The next card contains the values of the friction coefficients. Following are 14 cards specifying the concentration field, then 14 cards for the thickness

field, 14 for the puddle field, 14 cards for wind speed, then 21 cards for wind direction. Following are groups of 14 and 21 cards for the wind speed and direction for each of the forecast days.

Output of results

Results are printed in grid form with the outer boundary points omitted. The input concentration is reproduced as the first output. This is followed by grids of concentration, direction of movement, and distance for each of the five days. If the user has selected the optional melting forecast output, a melting concentration field and a thickness field will precede the above on each day.

TABLE B-1

Definition of variables

SCALE	scale factor
BLAT	base latitude
RHO	ice density
BEE	constant b
HEAT	heat absorbed by the water
YTIM	elapsed time since the start of the season
OPT	any number; if negative print option will occur
CONCICE	ice concentration
VELWIND	wind speed in knots
DIRWIND	wind direction plus 180
THICK	ice thickness in feet
TEMPICE	temporary storage location
UELX	x-component of ice speed
VELY	y-component of ice speed
DIST24	distance of ice drift in 24 hours in nautical miles
DIRICE	ice drift direction
XELT	thickness of ice melted
COMP	input thickness converted to centimeters
ZICE	a programmed unused storage location
WATEO	concentration of ice-free water
DEWATE	amount of growth of ice-free area
PUDLE	puddle data field
EXTRA	exponent
DTHICK	thickness change due to puddle growth
RHEAT	heat in puddle that increases puddle depth

TIME	in days, from the start of the forecast
PLAT	latitude, degrees
VELICE	ice drift speed
DCDT	change in concentration with time
YICE, YYICE	
SICE, XXICE	temporary storage locations
AKA	coefficient of friction between air and water
AKW	coefficient of friction between ice and water
RHOAIR	air density
DSUBW	water density
OMEGAB	coriolus acceleration
XI	variable
ENN	a constant
ALFA	drift deviation angle
BETA	$90 - \alpha$
SQMASS	mass of the ice
BBB	B , a constant
PSIO	an angle
PSI	an angle
CONFAC	modifying factor
VVICE	ice drift in meters per second
C	constant, normally one


```

PROGRAM ICEGRID MODIFIED
C THIS PROGRAM COMPUTES STEERING VECTORS AND CHANGES IN CONCENTRATION OF
C ICE AT SPECIFIC GRID POINTS IN 24 HOUR STEPS FOR A 5 DAY FORECAST.
C THE OUTPUT IS MODIFIED BY A SECTION WHICH COMPUTES CHANGES DUE TO
C MELTING. AN OPTIONAL PRINT OF THE MELTING FORECAST IS AVAILABLE.
C CONVERTS DEGREES TO RADIAN.
  RANGLE(DEGANG)=DEGANG*.017453
  PRINT 31
31 FORMAT(/////////120H)
  1 BY NAUTICAL MILE GRID EAST AND SOUTH FROM 75N 70W
  2
  PRINT 666
666 FORMAT(/////////120H)
  INPUT CONCENTRATION
  2
  DIMENSION CONCICE(26,21),VELWIND(26,21),DIRWIND(26,21),THICK
  1(26,21),TEMPICE(26,21),UELX(26,21),VELY(26,21),DIST24(26,21),
  2DIRICE(26,21),XELT(26,21),COMP(26,21),ZICE(26,21),WATEO(26,21),
  3DEWATE(26,21),PUDLE(26,21),EXTRA(26,21),DTHICK(26,21)
  READ 55,SCALE,BLAT,RHO,BEE,HEAT,YTIM,OPT
  C SCALE FACTOR FOR THE GRID.
  55 FORMAT(7F10.5)
  C BASE LATITUDE.
  1001 FORMAT(2F10.5)
  READ1002,AKA,WKW
  1002 FORMAT(2F10.5)
  READ 10,((CONCICE(I,J),J=1,21),I=1,26)
  C READ IN INITIAL CONCENTRATION.
  10 FORMAT(39F2.1)
  READ 237,((THICK(I,J),J=1,21),I=1,26)
  237 FORMAT (39F2.0)
  READ 23,((PUDLE(I,J),J=1,21),I=1,26)
  23 FORMAT(39F2.1)
  PRINT 777,((CONCICE(M,N),N=2,20),M=2,25)
  777 FORMAT(F9.2,18F6.2,////)
  TIME=1
  DO 1964 KJ=1,5

```



```

DO 11 JI=1,26
DO 11 KI=1,21
IF(THICK(JI,KI)-9.0)13,14,14
C CONVERTS FEET TO CENTIMETERS
13 COMP(JI,KI)=THICK(JI,KI)*12.0*2.54
C COMPUTES AMOUNT MELTED
XELT(JI,KI)=(BEE*TIME**2.0)/(2.0*RHO*(.208*YTIM+57.4))
THICK(JI,KI)=COMP(JI,KI)-XELT(JI,KI)
IF(THICK(JI,KI))208,208,107
208 THICK(JI,KI)=0.0
GO TO 107
14 THICK(JI,KI)=9.0
107 IF(CONCICE(JI,KI)-2.0)108,109,109
109 CONCICE(JI,KI)=2.0
GO TO 11
108 WATEO(JI,KI)=1.0-CONCICE(JI,KI)
IF(WATEO(JI,KI)-1.0)17,28,28
28 CONCICE(JI,KI)=0.0
THICK(JI,KI)=0.0
GO TO 11
17 IF(CONCICE(JI,KI)-1.0)27,18,18
18 IF(PUDLE(JI,KI))11,11,467
C COMPUTES CONCENTRATION CHANGE
27 EXTRA(JI,KI)=HEAT*TIME/(RHO*THICK(JI,KI))*(.208*YTIM+57.4))
DEWATE(JI,KI)=WATEO(JI,KI)*EXPF(EXTRA(JI,KI))
CONCICE(JI,KI)=1.0-DEWATE(JI,KI)
THICK(JI,KI)=THICK(JI,KI)*.39/12.0
IF(THICK(JI,KI))113,113,11
GO TO 11
467 IF(PUDLE(JI,KI)-.6)432,609,609
432 IF(YTIM-40.0)546,546,609
546 RHEAT=.1*HEAT+(.0175*YTIM)
GO TO 611
609 RHEAT=.8*HEAT
611 DTHICK=(RHEAT*TIME)/(RHO*(.208*YTIM+57.4))

```



```

IF(DTHICK(JI,KI)-THICK(JI,KI))19,20,20
C CONVERTS CENTIMETERS TO FEET
19 THICK(JI,KI)=THICK(JI,KI)*.39/12.0
IF(THICK(JI,KI))155,155,36
155 THICK(JI,KI)=0.0
GO TO 36
20 CONCICE(JI,KI)=.9
THICK(JI,KI)=THICK(JI,KI)*.39/12.0
IF(THICK(JI,KI))113,113,11
113 THICK(JI,KI)=0.0
GO TO 11
36 CONCICE(JI,KI)=1.0
11 CONTINUE
IF(OPT)762,791,791
762 PRINT 47((CONCICE(M,N),N=2,20),M=2,25)
47 FORMAT (F9.2,18F6.2////)
PRINT 901,((THICK(M,N),N=2,20),M=2,25)
901 FORMAT(F9.2,18F6.2////)
791 YTIM=YTIM+1.0
READ 12,((VELWIND(J,K),K=1,21),J=1,26)
C READ IN WIND SPEED.
12 FORMAT(39F2.0)
280 READ 697,((DIRWIND(J,K),K=1,21),J=1,26)
C READ IN WIND DIRECTION
697 FORMAT(26F3.0)
DO 51 JI=1,26
DO 51 KI=1,21
IF(CONCICE(JI,KI)-1.0)52,52,53
53 IF(CONCICE(JI,KI)-2.0)54,51,51
54 CONCICE(JI,KI)=1.0
52 IF(CONCICE(JI,KI))50,51,51
50 CONCICE(JI,KI)=0.0
51 CONTINUE
C CONCENTRATIONS LESS THAN 0,GREATER THAN 1, RESET TO 0,1 RESPECTIVELY.
DO 101 MM=1,26
DO 101 NN=1,21

```



```

XMM=MM
PLAT=BLAT-XMM/SCALE
C COMPUTES LATITUDE
CALL ICEFOR2(PLAT,VELWIND(MM,NN),DIRWIND(MM,NN),THICK(MM,NN),
1CONCICE(MM,NN),VELICE,DIRICE(MM,NN),DIST24(MM,NN),AKA,WKW)
C ENTERS SUBPROGRAM TO COMPUTE ICE DRIFT
UELX(MM,NN)=VELICE*SINF(RANGLE(DIRWIND))
101 VELY(MM,NN)=VELICE*COSF(RANGLE(DIRWIND))
C FOLLOWING DETERMINES CONCENTRATION TO BE USED AT LAND POINTS DEPENDANT
C ON ONSHORE/OFFSHORE WINDS.
DO 102 IJ=2,26
DO 102 KL=2,20
IF(CONCICE(IJ,KL)-2.0) 6,7,6
7 DCDT=0.0
GOTO 102
6 IF(CONCICE(IJ-1,KL)-2.0)76,75,76
75 IF(VELY(IJ,KL))77,77,78
78 YICE=1.0
GOTO 79
77 YICE=0.0
GOTO 79
76 YICE=CONCICE(IJ-1,KL)
79 IF(CONCICE(IJ+1,KL)-2.0)80,81,80
81 IF(VELY(IJ,KL))82,83,83
82 YYICE=1.0
GOTO 84
83 YYICE=0.0
GOTO 84
80 YYICE=CONCICE(IJ+1,KL)
84 IF(CONCICE(IJ,KL-1)-2.0)85,86,85
86 IF(UELX(IJ,KL))87,88,88
88 XICE=0.0
GOTO 89
87 XICE=1.0
GOTO 89
85 XICE=CONCICE(IJ,KL-1)

```



```

89 IF(CONCICE(IJ,KL+1))-2.0)90,91,90
91 IF(UELX(IJ,KL))92,92,93
92 XXICE=0.0
   GOTO 16
93 XXICE=1.0
   GOTO 16
90 XXICE=CONCICE(IJ,KL+1)
16 DCDT=(-CONCICE(IJ,KL)*((UELX(IJ,KL-1)-UELX(IJ,KL+1))/120.+
  1(VELY(IJ-1,KL)-VELY(IJ+1,KL))/120.)-UELX(IJ,KL))*((XICE-XXICE)/
  2120.)-VELY(IJ,KL))*((YICE-YYICE)/120.))*SCALE
C COMPUTES CHANGE IN CONCENTRATION.
102 TEMPICE(IJ,KL)=CONCICE(IJ,KL)+24.*DCDT
C COMPUTES AND TEMPORARILY STORES NEW CONCENTRATIONS.
   DO 103 IM=2,25
   DO 103 IN=2,20
     CONCICE(IM,IN)=TEMPICE(IM,IN)
     IF(CONCICE(IM,IN)-2.0)672,673,673
673 CONCICE(IM,IN)=2.0
     GO TO 103
672 IF(CONCICE(IM,IN)-1.0)671,670,670
670 CONCICE(IM,IN)=1.0
     GO TO 103
671 IF(CONCICE(IM,IN))587,587,103
587 CONCICE(IM,IN)=0.0
103 CONTINUE
C FOLLOWING PRINT OUTPUTS.
   PRINT 222
222 FORMAT(/120H1
  1ONCENTRATION FIELD
  2 ///)
   PRINT 99,((CONCICE(I,J),J=2,20),I=2,25)
   PRINT 333
333 FORMAT(/120H1
  1ON OF MOVEMENT FIELD
  2 ///)
   PRINT 66,((DIRICE(K,L),L=2,20),K=2,25)

```

C

DIRECTI


```

PRINT 444
444 FORMAT(//120H1
1 DISTANCE FIELD
2 ///)
1964 PRINT 66,((DIST24(M,N),N=2,20),M=2,25)
99 FORMAT(F9.2,18F6.2/////
66 FORMAT(F9.1,18F6.1/////
END
SUBROUTINE ICEFOR2(PLAT,VELWIND,DIRWIND,THICK,CONCICE,VELICE,
1DIRICE,DIST24,AKA,WKW)
C THIS SUBROUTINE COMPUTES ICE DRIFT USING SHULEIKENS EQUATIONS MODIFIED
C FOR CONCENTRATION.
VMTRSF(VNMHR)=VNMHR*.514775
C CHANGES KNOTS TO METERS PER SECOND.
RANGLE(DEGANG)=DEGANG*.017453
C CONVERTS DEGREES TO RADIAN.
ROOT2=SQRTF(2.)
C=1.
RHOAIR=1.3E-3
DSUBW=1.03
ENN=1.88139E8*AKA*RHOAIR/DSUBW
FRICT=(AKA*RHOAIR)/(WKW*DSUBW)
OMEGAB=7.29121E-5*SINF(RANGLE(PLAT))
XI=SQRTF(3.14159*WKW/(ENN*OMEGAB*ROOT2))
ALFA=ACTNF(XI*ROOT2+1.)
BETA=3.14159/4.-ALFA
ACOSA=COSF(ALFA)
BCOSB=COSF(BETA)
FACT=XI*ACOSA+BCOSB
SQMASS=THICK*28.6512
BBB=(2.*SQMASS*OMEGAB*FACT**2)/(WKW*DSUBW*BCOSB)*.01
IF(CONCICE-2.0)5,4,5
4 DIRICE=0.0
VELICE=0.0
DIST24=0.0
GOTO 3

```



```

5 IF (VELWIND) 2,1,2
1 VELICE=0.0
DIRICE=DIRWIND+90.
DIST24=0.
GOTO 3
2 PSIO=0.0
DELPSI=.00873
CONFAC=(1.+(1.-CONCICE)/2.)*(1.+3.*VELWIND*.01))
431 DO 20 KK=1,180
PSI=ATANF(TANF(BETA)+BBB/(C*VMTRSF(VELWIND))*FACT*SQRTF
1*(FRICT*COSF(PSIO)/BCOSB)*CONFAC))
DIFPSI=PSI-PSIO
IF(DIFPSI-.00436) 25,25,20
20 PSIO=PSIO+DELPSI
25 VVICE=C*VMTRSF(VELWIND)*FACT*SQRTF(FRICT*COSF(PSI)/BCOSB)
1 *CONFAC
VELICE=VVICE/.514775
DIRICE=DIRWIND+PSI/.017453

IF (DIRICE-360.) 21,22,22
22 DIRICE=DIRICE-360.
21 DIST24= VELICE * 24.
IF (CONCICE-2.0) 3,4,3
3 RETURN
END
END

```


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